Detecting Reliable Instances for Learning



Judy Hoffman Adversarial Machine Learning in Computer Vision **CVPR Workshop 2021**



Standard Supervised Learning



Standard Supervised Learning





Random Sampling

Incorrect Label



Label: "Cat" **Prediction:** "Cat"

Label: "Dog" **Prediction:** "Cat"

Potential Data Pitfalls

Adversarial Manipulations

Variable Difficulty



Label: "Dog" **Prediction:** "Cat"



Incorrect Label



Learning with Noise





Label: "Cat" **Prediction:** "Cat"

Label: "Dog" **Prediction:** "Cat"

Potential Data Pitfalls

Adversarial Manipulations

Variable Difficulty

Curriculum Learning

Label: "Dog" **Prediction:** "Cat"



Enforcing Reliability

Adversarial Examples



 $+.007 \times$

 $\boldsymbol{\mathcal{X}}$

"panda" 57.7% confidence



 $sign(\nabla_{\boldsymbol{x}} J(\boldsymbol{\theta}, \boldsymbol{x}, y))$

"nematode" 8.2% confidence



[Goodfellow et al. ICLR 2015]



Training point



28







Sweep over a grid of





Perturbed Image





MNIST LeNet Decisions Around Training Point

Non-smooth Decision Boundary

Small perturbations lead to new outputs



g 8 3

Adversarial Training



[Madry et. al. ICLR 18]



Adversarial Stability

Panda



Instance Adaptive Adversarial Training



Balaji, Goldstein, Hoffman. arXiv 2020.

Adversarial Training



[Madry et. al. ICLR 18]



Instance Adaptive Adversarial Training



Balaji, Goldstein, Hoffman. arXiv 2020.

Instance Adaptive Adversarial Training



(a) Samples from bottom 1% ϵ

Balaji, Goldstein, Hoffman. arXiv 2020.

(b) Samples from top 1% ϵ

Adaptive Adversarial Training: CIFAR-10



Balaji, Goldstein, Hoffman. arXiv 2020.

Semi-supervised Learning

Labeled Data



Unlabeled Data





Leverages labeled data to "pseudo-label" unlabeled data

Adversarial Training



[Madry et. al. ICLR 18]



Virtual Adversarial Training



[Miyato et. al. ICLR 2016]



Virtual Adversarial Training



[Miyato et. al. ICLR 2016]



Unsupervised Domain Adaptation







Target Data

Unlabeled





Shu et. al. ICLR 2018

Example: Entropy Minimization





Supervised Decision Boundary



Example: Entropy Minimization

Error Accumulation





oeled Ounlabeled ---- Class boundary

Self-Training with Unreliable Instances

 Under a domain shift, some target categories may be misaligned

 Entropy minimization on such instances would increase model confidence, reinforcing errors

$$egin{aligned} \mathcal{L}_{CEM} &= \mathbb{E}_{\mathbf{x} au \sim \mathcal{P}_{\mathcal{T}}}[\mathcal{H}_{\Theta}(y \mid \mathbf{x}_{\mathcal{T}})] \ &= \mathbb{E}_{\mathbf{x}_{\mathcal{T}} \sim \mathcal{P}_{\mathcal{T}}} \Big[\sum_{c=1}^{C} -p_{\Theta}(y = c \mid \mathbf{x}_{\mathcal{T}}) \log p_{\Theta}(y = c \mid \mathbf{x}_{\mathcal{T}})$$

Entropy Minimization for UDA



Poor Initialization



 $c \mid \mathbf{x}_{\mathcal{T}})$



Self-Training with Unreliable Instances

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Entropy Minimization for UDA



Poor Initialization

Classes =
$$\{ \bigcirc, \land \}$$
 Source \bigcirc Labeled \bigcirc Class boundar



Prior Work: Measure Image Aug Differences



Natural and Adversarial Error Detection using Invariance to Image Transformations. Bahat, Irani, Shakhnarovich, arXiv 2019

Detecting Errors



Learned Invariance (Contrastive Learning)

SENTRY Selective Entropy Optimization via Committee Consistency for Unsupervised Domain Adaptation



Viraj Prabhu



Shivam Khare





Deeksha Karthik



Judy Hoffman



Key Idea

- Identify reliable instances 1. using predictive consistency^{1,2,3}
 - Model confidence is known to be uncalibrated under distribution shift [Ovadia NeurIPS 2019]
- 2. Increase model confidence on highly consistent target instances, reduce on inconsistent

- Bahat et al. arXiv 2019.
- Chen et al. ICML 2020. 2.
- Sohn et al., NeurIPS 2020. 3.

SENTRY: Selective Entropy Optimization via Committee Consistency



Prabhu, Khare, Karthik, Hoffman. arXiv:2012.11460, 2021



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SENTRY: Selective Entropy Optimization via Committee Consistency



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Class Balancing Sampled w/





Class Balancing Sampled w/





































Selective Entropy Loss







I. Peng et al., ICCV 2019.

2. Tan et al., ECCVW 2020.

SENTRY Results: Image Classification

MiniDomainNet^{1,2}



Prabhu, Khare, Karthik, Hoffman 2021



SENTRY Results: MiniDomainNet

3.

4.

5.

6.

8.



MiniDomainNet (40 classes, 12 shifts)

SENTRY Results: Office Home

Custom label shifts²



I. Venkateswara et al., CVPR 2017. 2. Tan et al., ECCVW 2020.

Office Home¹









SENTRY Results: Office Home



Wu et al., ICML 2019. Jiang et al., ICML 2020.

Tan et al., ECCVW 2020. Long et al., NeurIPS 2018.

OfficeHome-LDS (65 classes, 6 shifts)

InstaPBM MDD+I.A.SENTRY

Li et al., arXiv 2020. Zhang et al., ICML 2019





Results: Controlling Target Distribution

MNIST-LT label histograms



Long et al., ICML 2015.

Ganin et al., ICML 2015.



SVHN→ MNIST-LT

Tan et al., ECCVW 2020.

Li et al., arXiv 2020.

Ablating SENTRY: Selection





Prabhu, Khare, Karthik, Hoffman. arXiv:2012.11460, 2021



Key Idea: Decide when to learn

Learning can be derailed by

- Unreliable labels
 - Label noise
 - Manipulated
 - Model misalignment
- Unreliable samples
 - Inherently ambiguous
 - Different from prior data
 - Manipulated

Summary



Thank you



Sean Foley



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Arvind Krishnakumar



Rohit Mittapali



Kartik Sarangmath









Key Idea: Decide when to learn





